

# Approximation of Geometric Data

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# Outline

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- 2 Approximation of manifold-valued functions

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- 3 Approximation using B-spline

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Example: Liquid Crystals



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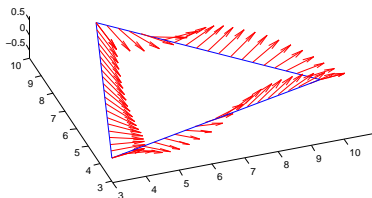
$$f : \Omega \subset \mathbb{R}^3 \rightarrow S^2 = \{x \in \mathbb{R}^3 \mid \|x\|_2 = 1\}$$

## Boundary value problem with sphere-valued function

Given  $\Omega \subset \mathbb{R}^2$  and  $g : \delta\Omega \rightarrow S^2$  we are interested in minimizing the energy

$$f_{opt} = \operatorname{argmin}_{f: \Omega \rightarrow S^2} \int_{\Omega} \|\nabla f(x)\|^2 dx$$

subject to  $f = g$  on  $\delta\Omega$ . Here  $\|\nabla f(x)\|^2 = \sum_{i=1}^3 \sum_{j=1}^2 \left( \frac{df_i(x)}{dx_j} \right)^2$ .





# Other Applications

- Rigid Body Motion
- Image Processing
- Diffusion Tensor Imaging
- ...

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How to solve optimization problems numerically?

- Characterize the solution  $u$  as the minimum of some functional  $J$  on a function space  $V$ .
- Consider a subspace  $V_h$  of functions which can be handled by a computer, i.e. each function is characterized by finitely many values.
- Find the minimum  $u_h$  of the functional on this subspace.

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### Theorem ((Linear) Céa)

Let  $\mathbf{a}$  be a coercive bilinear form,  $\mathbf{L}$  a linear form and  $u$  and  $u_h$  the solution of

$$\mathbf{a}(u, v) = L(v) \quad \forall v \in V \text{ (resp. } V_h)$$

then

$$\|u - u_h\| \leq C \operatorname{argmin}_{w \in V_h} \|w - u\|.$$

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### Theorem (Grohs, Hardering, Sander 2012)

If  $J$  is elliptic along geodesic homotopies.

$$D(u, u_h) \leq C \operatorname{argmin}_{w \in V_h} D(w, u)$$

where  $D$  is a distance function.

In order to bound the error between the exact solution and the approximation by geodesic finite elements we need to bound the best approximation error of the "finite element space".



# How to interpolate manifold-valued functions?

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If  $Q^h$  is exact for constant functions we have

$$\sum_{i \in I} \psi_i(x) = 1.$$

hence for all  $x \in \mathbb{R}^n$ ,  $Q^h f(x)$  is an weighted average of function values at the grid points.

For points  $x_1, \dots, x_n \in M$  and weights  $\lambda_1, \dots, \lambda_n \in \mathbb{R}$  with sum 1 we define the Riemannian average by

$$av_M((x_i)_{i=1}^n, (\lambda_i)_{i=1}^n) = \underset{x^* \in M}{\operatorname{argmin}} \sum_{i=1}^n \lambda_i d^2(x^*, x_i).$$

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If  $M = \mathbb{R}^m$  the Riemannian average reduces to the affine combination. Hence  $av_M$  is a generalization of affine combinations to the manifold-valued setting.



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The "finite element space" is

$$\{x \mapsto av_M((c_i)_{i \in I}, (\psi_i(h^{-1}x))_{i \in I}) \mid c_i \in M \text{ s.t. } av \text{ well defined}\}.$$

Each function can be represented by the values  $(c_i)_{i \in I}$ .



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### Theorem (Jackson)

*If  $M = \mathbb{R}^m$ ,  $f \in C^k$  and  $Q^h$  is exact for polynomials of degree smaller than  $k$  then*

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### Theorem (Grohs, Hardering, Sander)

*For Lagrange-Interpolation (i.e.  $\psi_i(x_j) = \delta_{ij}$ ) the above statement is true for  $l = 1$  and the  $L_\infty$  as well as the  $L_2$ -norm.*



Lagrange Interpolation is numerically not stable.

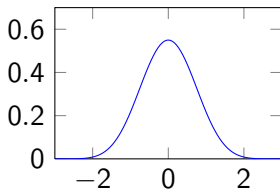
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For odd  $m \in \mathbb{N}$  there exists  $B_m: \mathbb{R} \rightarrow \mathbb{R}$  such that

- $B_m \in C^{m-1}$
- $\text{supp}(B_m) = [-(m-1)/2, (m-1)/2]$
- $B_m|_k^{k+1} \in \Pi_m$  for all  $k \in \mathbb{N}$



$$\{x \mapsto av_M((c_i)_{i \in I}, (B_m(h^{-1}x - i))_{i \in I}) \mid c_i \in M\}.$$

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Spline functions are only exact for polynomials of degree 1.

But we can consider linear combinations of the shifted spline function which are exact for polynomials up to degree  $n$ .

$$\phi_m(x) = \sum_{j=-(m-1)/2}^{(m-1)/2} a_j B_m(x - j).$$

E.g. if  $m = 3$  then  $(a_{-1}, a_0, a_1) = (-1/6, 4/3, -1/6)$  if  $m = 5$  then  $(a_{-2}, \dots, a_2) = (13/240, -7/15, 73/40, -7/15, 13/240)$

If  $M = \mathbb{R}^n$  :

$$Q^h f(x) = \sum_i \phi_m(h^{-1}x - i) f(hi) \quad (1)$$

$$= \sum_{ij} a_j B_m(h^{-1}x - i - j) f(hi) \quad (2)$$

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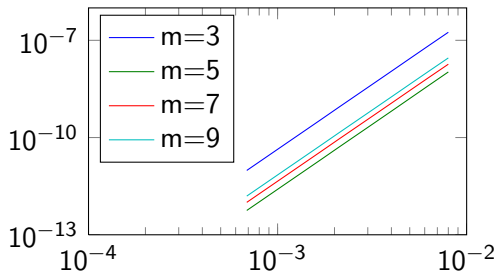
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## Numerical experiment

$$\mathbb{R} \rightarrow S^2 : x \mapsto \begin{pmatrix} \cos(\cos(x) + 1) \cos(\cos(x)) \\ \cos(\cos(x) + 1) \sin(\cos(x)) \\ \sin(\cos(x) + 1) \end{pmatrix}.$$

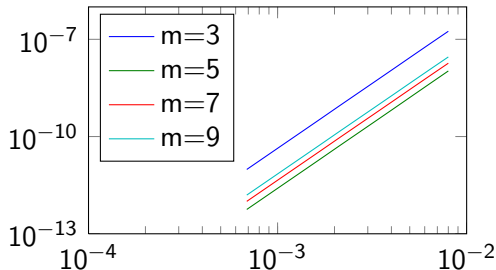
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Only order 4 approximation!

For other approximations using subdivisions a similar behavior has been observed. [G. Xie and T. Yu]

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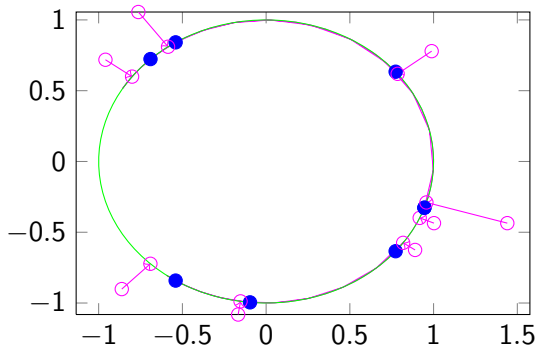
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 Are there any higher order approximations?

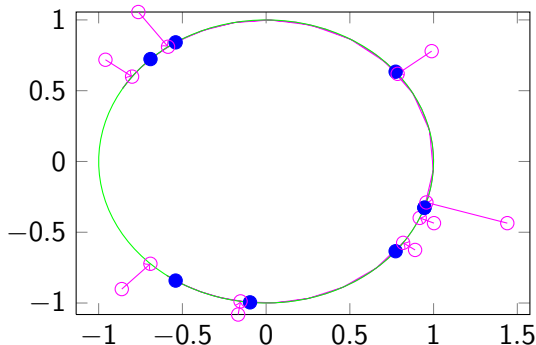
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In general  $\sum_j a_j f(h(k-j)) \notin M$  hence  $P_M$  needed.

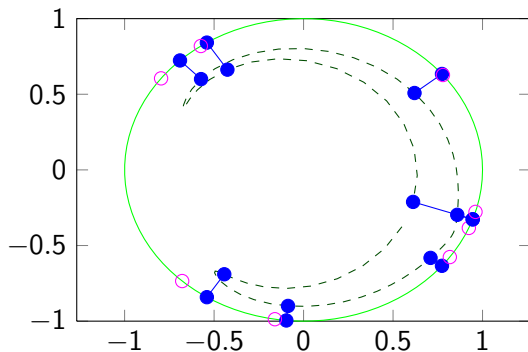


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# Orthonormal Perturbations



Consider  $\bar{f}(x) = g_h(x)f(x)$  with  $g_h: \mathbb{R} \rightarrow \mathbb{R}_+$  such that

$$\sum_j a_j \bar{f}(h(k-j)) \in M.$$

Consider a 1-periodic function  $f: \mathbb{R} \rightarrow S^m$ .

Let  $n = 1/h$  and  $z_1, \dots, z_n \in \mathbb{R}$  such that

$$c_k := \sum_j a_j(z_{k-j} f(h(k-j))) \in S^m \quad (4)$$

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### Theorem

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### Theorem

*For  $h$  small enough there is exactly one solution  $z_1, \dots, z_n$ .*

We can define a 1-periodic function  $g_h: \mathbb{R} \rightarrow \mathbb{R}_+$  and

$$\bar{f}_h(x) = f(x)g_h(x) \quad (5)$$

such that

$$\sum_j a_j \bar{f}(x + h(k-j)) \in S^m \quad (6)$$

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Proof:

$$\left\| f(x) - P_M \left( \sum_k B_m(h^{-1}x - k) c_k \right) \right\| \quad (7)$$

$$\leq \left\| P_M(\bar{f}(x)) - P_M \left( \sum_i \phi_m(h^{-1}x - i) \bar{f}(hi) \right) \right\| \quad (8)$$

$$\leq C_1 \left\| \bar{f}(x) - \left( \sum_i \phi_m(h^{-1}x - i) \bar{f}(hi) \right) \right\| \quad (9)$$

$$\leq C_2 h^\alpha \quad (10)$$

How to compute  $c_k$ ?

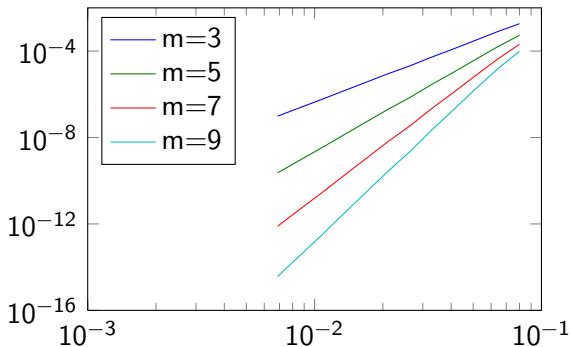
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Let  $f_1, \dots, f_d$  be the values of  $f$  at the points  $h, 2h, \dots$  and let  $g_1, \dots, g_d$  be our unknowns such that  $g_h(hi) = g_i$ . As before let  $c_i = \sum_k a_k f_{i-k} g_{i-k}$ . We find the solution by solving the system of equations

$$\langle c_i, c_i \rangle - 1 = 0 \quad \forall i \in \{1, \dots, n\}$$

using Newton's Method.

Numerical Test:  $\mathbb{R} \rightarrow S^2 : x \mapsto \begin{pmatrix} \cos(4 \cos(x)) \cos(5 \cos(x)) \\ \cos(4 \cos(x)) \sin(5 \cos(x)) \\ \sin(4 \cos(x)) \end{pmatrix}.$



## Some Remarks

- Generalization to Manifolds which are given as  $M = \{x \in \mathbb{R}^K : g(x) = 0\}$  where  $g: \mathbb{R}^K \rightarrow \mathbb{R}^L$  and  $Dg$  is of maximal rank is possible.
- Existence of quasiinterpolation operator already sufficient for analysis of numerical solution of PDEs

Thank You for your attention!  
Any Questions?