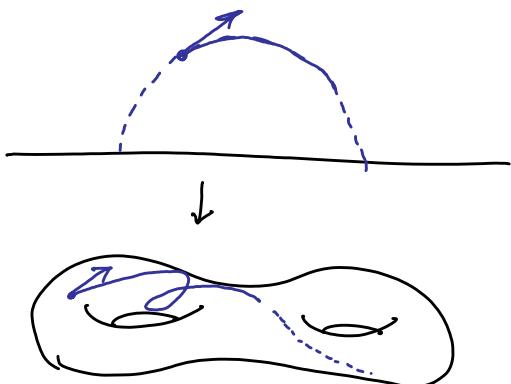


Lecture 3: Geodesic flow.

$\Gamma \subset SL_2(\mathbb{R})$ - lattice subgroup,
 $M = \Gamma \backslash H$ - hyperbolic subgroup, $|M| < \infty$.

Geodesic flow



$$T' H \cong PSL_2(\mathbb{R})$$

$$T'M \cong \Gamma \backslash PSL_2(\mathbb{R})$$

$$g_t: T'M \rightarrow T'M$$

$$g_t: \Gamma \backslash PSL_2(\mathbb{R}) \rightarrow \Gamma \backslash PSL_2(\mathbb{R})$$

$$x \mapsto x \cdot \underbrace{\begin{pmatrix} e^{t/2} & 0 \\ 0 & \bar{e}^{-t/2} \end{pmatrix}}_{a_t}$$

$$X = T'M \cong \Gamma \backslash PSL_2(\mathbb{R}).$$

Let $\mu = \frac{dx dy}{y^2} d\theta$ be the measure on $T'M$,
 where $d\theta$ is the Lebesgue measure on S^1 .
 For $g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(\mathbb{R})$, $g: (z, v) \mapsto \left(\frac{az+b}{cz+d}, \frac{v}{(cz+d)^2} \right)$.
 It is easy to check that μ is left $SL_2(\mathbb{R})$ -inv.,

i.e. defines left inv. measure on $PSL_2(\mathbb{R})$.

Because of invariance, μ also gives a measure on $X = \pi|T'M$.

Since $|M| < \infty$, $\mu(X) < \infty$.

We normalise μ so that $\mu(X) = 1$.

In fact, μ is also right invariant.

(one can deduce this from uniqueness of inv. measure on $PSL_2(\mathbb{R})$).

In particular, μ is g_t -inv.

Def 1) g_t is ergodic if for every measurable $A \subset X$ which is g_t -inv., we have $\mu(A) = 0$ or 1.

2) g_t is mixing if for every measurable $A, B \subset X$,
 $\mu(A \cap g_t^{-1}B) \rightarrow \mu(A)\mu(B)$ as $t \rightarrow \infty$.

Thm. The geodesic flow is mixing.

For $g \in SL_2(\mathbb{R})$ and $\varphi \in L^2(X)$, define

$$\pi(g)\varphi(x) = \varphi(x \cdot g).$$

Note that $\pi(g_1 g_2) = \pi(g_1) \pi(g_2)$.

By invariance of μ , $\|\pi(g)\varphi\|_2^2 = \int_X |\varphi(xg)|^2 d\mu(x) = \|\varphi\|_2^2$,
i.e., $\pi(g): L^2(X) \rightarrow L^2(X)$ is unitary.

Since $\mu(A \cap g_t^{-1}B) = \langle \chi_A, \pi(a_t) \chi_B \rangle$,

mixing is equivalent to

$$\langle \varphi, \pi(a_t)\psi \rangle \xrightarrow{t \rightarrow \infty} \left(\int_X \varphi d\mu \right) \left(\int_X \bar{\psi} d\mu \right).$$

for all $\varphi, \psi \in L^2(X)$.

Lem. The map $SL_2(\mathbb{R}) \rightarrow L^2(X): g \mapsto \pi(g)\varphi$
is continuous.

Hint: $C_c(X) \subset L^2(X)$ is dense.

Proof of Thm.

Without loss of generality, $\int_X \varphi d\mu = \int_X \psi d\mu = 0$.

Suppose then that for some φ, ψ and $t_n \rightarrow \infty$,

$$\langle \varphi, \pi(a_{t_n})\psi \rangle \not\rightarrow 0.$$

Weak convergence: $\varphi_n \xrightarrow{\text{weak}} \varphi$ if $\langle \varphi, \varphi_n \rangle \rightarrow \langle \varphi, \varphi \rangle$
for all $\varphi \in L^2(X)$.

Banach-Alaoglu Thm Closed bounded subsets of $L^2(X)$
are compact in weak topology.

Since $\|\pi(a_{t_n})\varphi\| = \|\varphi\|$, passing to a subsequence,
we may assume that $\pi(a_{t_n})\varphi \rightarrow \tilde{\varphi} \in L^2(X)$.

Claim $\tilde{\varphi}$ is invariant under $U = \{u_s = \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix}\}$.

$$\begin{aligned} \text{We use that } \bar{a}_{t_n}^{-1} u_s a_{t_n} &= \begin{pmatrix} e^{t_n/2} & 0 \\ 0 & e^{-t_n/2} \end{pmatrix}^{-1} \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix} \begin{pmatrix} e^{t_n/2} & 0 \\ 0 & e^{-t_n/2} \end{pmatrix} \\ &= \begin{pmatrix} 1 & e^{-t_n}s \\ 0 & 1 \end{pmatrix} = u_{e^{-t_n}s} \rightarrow e. \end{aligned}$$

$$\pi(u_s) \tilde{\varphi} = \underset{n \rightarrow \infty}{w\text{-lim}} \pi(u_s) \pi(a_{t_n}) \varphi = \underset{n \rightarrow \infty}{w\text{-lim}} \pi(a_{t_n}) \pi(u_{e^{-t_n}s}) \varphi$$

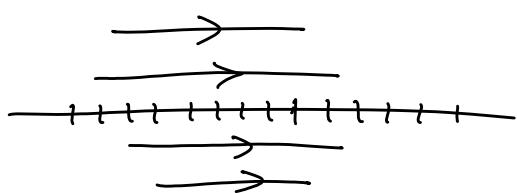
$$\|\pi(a_{t_n}) \pi(u_{e^{-t_n}s}) \varphi - \pi(a_{t_n}) \varphi\| = \|\pi(u_{e^{-t_n}s}) \varphi - \varphi\| = 0.$$

$$\text{Hence, } \pi(u_s) \tilde{\varphi} = \underset{n \rightarrow \infty}{w\text{-lim}} \pi(a_{t_n}) \varphi = \tilde{\varphi}. \quad \boxed{}$$

Consider the function $F(g) = \langle \pi(g) \tilde{\varphi}, \tilde{\varphi} \rangle$, $g \in SL_2(\mathbb{R})$.
Then $F(U \cdot g \cdot U) = F(g)$.

Note that $SL_2(\mathbb{R})/\mathcal{U} \simeq \mathbb{R}^2 \setminus \{(0)\}$: $g\mathcal{U} \mapsto ge_1$,
so F gives a \mathcal{U} -inv. function on $\mathbb{R}^2 \setminus \{(0)\}$.

$$\mathcal{U} \curvearrowright \mathbb{R}^2: \begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x+sy \\ y \end{pmatrix}$$



Orbits $\left\{ \begin{array}{l} \text{lines } y=c, c \neq 0 \\ \text{points } \{(x, 0)\} \end{array} \right.$

$F = \text{const}$ on $y=c, c \neq 0$, and by continuity,
 $F = \text{const}$ on $y=0$.

$$\text{Then } \langle \pi(a_t) \tilde{\psi}, \tilde{\psi} \rangle = F(a_t \cdot e_i) = F(e) = \|\tilde{\psi}\|^2.$$

This gives equality in the Cauchy-Schwarz inequality, so $\pi(a_t) \tilde{\psi} = \lambda \tilde{\psi}$ and $\lambda = 1$.

Hence, F is B -biinvariant, $B = \left\{ \begin{pmatrix} a & * \\ 0 & \bar{a}^{-1} \end{pmatrix} : a > 0 \right\}$.

Since $B \cdot e_2 = \{y > 0\}$ and $B \cdot (-e_2) = \{y < 0\}$,

F is constant on $\{y > 0\}$ and $\{y < 0\}$, and

by continuity, F is constant, i.e.,

$$\langle \pi(g) \tilde{\psi}, \tilde{\psi} \rangle = \|\tilde{\psi}\|^2 \text{ for } g \in SL_2(\mathbb{R}).$$

As above, we deduce that $\pi(g) \tilde{\psi} = \tilde{\psi}$ for all g .

This means that for all g and a.e. x , $\tilde{\varphi}(gx) = \tilde{\varphi}(x)$.

Then by Fubini Thm, for a.e. $x \in X$,

$\{g : \tilde{\varphi}(gx) = \tilde{\varphi}(x)\}$ has full measure.

Since G acts transitively, $\tilde{\varphi} = \text{const}$ in $L^2(X)$.

We have $\langle \varphi, \pi(a_{t_n})\psi \rangle \rightarrow \langle \varphi, \tilde{\varphi} \rangle \neq 0$,

but $\langle 1, \pi(a_{t_n})\psi \rangle \rightarrow \langle 1, \tilde{\varphi} \rangle$.

$\overbrace{\hspace{10em}}$

This is a contradiction. }

Cor. For a.e. $x \in X$, $\{g_t x\}_{t \geq 0}$ is dense in X .

Distribution of orbits.

Mean Ergodic Thm. $\forall \varphi \in L^2(X)$:

$$\left\| \frac{1}{T} \int_0^T \varphi(g_t x) dt - \int_X \varphi d\mu \right\|_2 \xrightarrow[T \rightarrow \infty]{} 0.$$

$\overbrace{\hspace{10em}}$

This follows from mixing. }

Pointwise Ergodic Thm. $\forall \varphi \in L^2(X)$ a.e. $x \in X$:

$$\frac{1}{T} \int_0^T \varphi(g_t \cdot x) dt \xrightarrow{T \rightarrow \infty} \int_X \varphi d\mu.$$

Anosov property

Let $u_a = \begin{pmatrix} 1 & a \\ 0 & 1 \end{pmatrix}$ and $v_b = \begin{pmatrix} 1 & 0 \\ b & 1 \end{pmatrix}$.

Stable foliation: $\mathcal{W}^s(x) = \{x \cdot u_a : a \in \mathbb{R}\}$.

Unstable foliation: $\mathcal{W}^u(x) = \{x \cdot v_b : b \in \mathbb{R}\}$.

Properties:

1) (transversality) $T_x(g_R x) \oplus T_x \mathcal{W}^s(x) \oplus T_x \mathcal{W}^u(x) = T_x M$.

2) $g_t \mathcal{W}^s(x) = \mathcal{W}^s(g_t x)$, $g_t \mathcal{W}^u(x) = \mathcal{W}^u(g_t x)$

$$x \cdot u_a \cdot a_t = x \cdot a_t \cdot \underbrace{u_{e^t a}}$$

3) (contraction)

for $y \in \mathcal{W}^s(x)$, $d(g_t x, g_t y) \leq \text{const. } e^{-t} d(x, y)$;

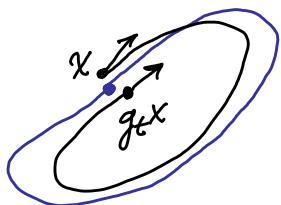
for $y \in \mathcal{W}^u(x)$, $d(g_{-t} x, g_{-t} y) \leq \text{const. } e^{-t} d(x, y)$.

Let $y = x \cdot u_a$. Then

$$\begin{aligned} d(g_t(x), g_t(y)) &= d(xa_t, xu_a \cdot a_t) = d(xa_t, x a_t \cdot u_a e^{-t}) \\ &\leq d(e, u_a e^{-t}) \leq \text{const} \cdot a e^{-t}. \end{aligned}$$

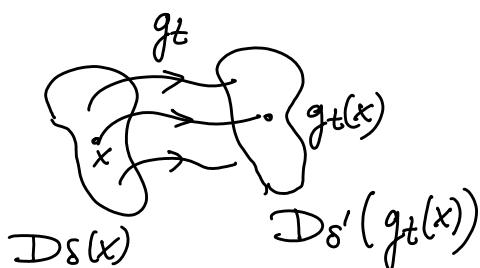
Anosov Closing Lemma.

Suppose that for some $x \in X$ and $t > 0$, $d(x, g_t(x)) < \varepsilon$.
Then \exists periodic $x_0 \in X$: $d(x, x_0) \leq \text{const} \cdot \varepsilon$.



$$D_s(x) = \{x \cdot u_a v_b : |a|, |b| < \delta\}.$$

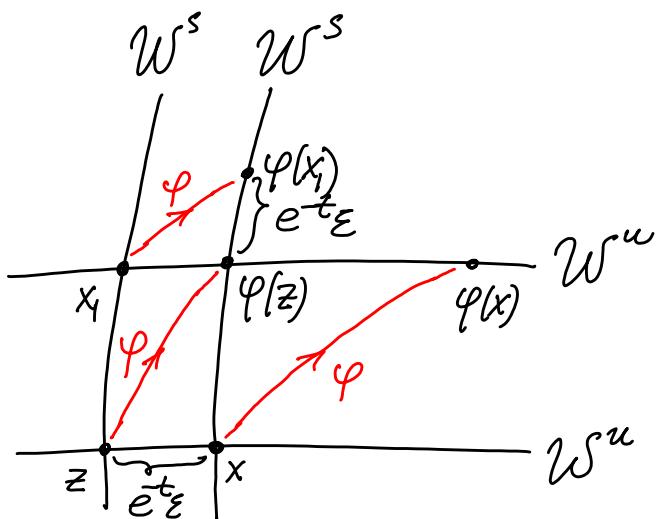
$D_s(x)$ is 2-dim. manifold transversal
to the flow; $g_t(D_s(x)) \subset D_{s'}(g_t(x))$.



$$\exists t_0 : |t_0| \leq \text{const} \varepsilon : g_{t+t_0}(x) \in D_s(x).$$

Consider the map:

$$\begin{aligned} \varphi : D_s(x) &\rightarrow D_{s'}(x) \\ y &\mapsto g_{t+t_0}(y) \end{aligned}$$



By transversality, $\exists z \in W^u(x) : \varphi(z) \in W^s(x)$.

$$\begin{aligned} \text{Then } d(z, x) &= d(g_{-t-t_0}(\varphi(z)), g_{-t-t_0}(\varphi(x))) \\ &< \text{const. } e^{-t} \cdot \varepsilon. \end{aligned}$$

Take $x_1 \in W^s(z) \cap W^u(\varphi(z))$.

$$\begin{aligned} \text{Then } d(\varphi(x_1), \varphi(z)) &\leq d(g_{t+t_0}(x_1), g_{t+t_0}(z)) \\ &< \text{const. } e^{-t} \cdot \varepsilon \end{aligned}$$

Hence, $d(x_1, \varphi(x_1)) < \text{const. } e^{-t} \cdot \varepsilon$.

Continuing this process, we construct x_∞ such that $\varphi(x_\infty) = x_\infty$. This gives a periodic orbit.

]

Cor. Periodic orbits of geodesic flow
are dense.